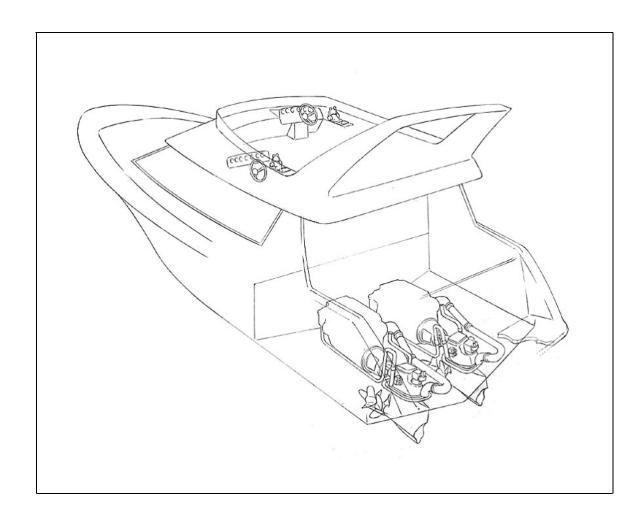
Volvo Penta Installation Check List D4/D6 with IPS Twin Installation (Version 2.4)



Boat/Vessel Manufacturer:

Boat/Vessel Model/Type:

Engine Installation/Type:

Hull Identification Number:



1 Check List Information

1.1 Issuer

Inspector	Date
Company	Phone
Address	City
Country	Email/Fax

1.2 Installation Approval

Volvo Penta does not make physical engine installations. This document shall be regarded as a tool to systematically check and assess the installation. That does not mean that the check and signature on this form that the responsibility is either shared or overtaken by the person doing the check. The responsibility for the installation remains with installing company or party.

Inspection subject to Volvo Penta Certified Installation:		
Yes: No: , if Yes, see procedure for Certified Installation.		
Certificate number		
Approval signatu	ure Date	

2 General Description

2.1 Contact and boat information

Contact person	Title	Phone
Address	City	Country
Contact person signature		Date
Hull material		
Fiber reinforced plastic	Steel	
Aluminum	Other	
Geometry		
LOA [m/ft]		Lwl [m/ft]
BOA [m/ft]		Bwl [m/ft]
Draft [m/ft]		Displacement [kg/lb.]
2.2 Engines		
Engine model (port)	Specification num	nber Serial number
Engine model (starboard)	Specification num	nber Serial number
Rating/hp		Rated RPM
VP standard specification		Front end PTO
Yes: No:		Yes: No:
2.3 Transmission and propulsion		
	- '-	DramallarTima/Sima
Drive type and Model	Reduction ratio	PropellerType/Size
IPS		
Drive serial number (port)		Drive serial number (starboard)

3 Installation

3.1 Hull shape and IPS placement and engine bed

Checked Remarks: 3.1.2 Clearance around IPS installation, hull must be flat Checked Remarks: 3.1.3 Engine bed design and structural strength, lamination, etc Checked: Remarks:
3.1.2 Clearance around IPS installation, hull must be flat Checked Remarks: 3.1.3 Engine bed design and structural strength, lamination, etc Checked: Remarks:
hull must be flat Checked Remarks: 3.1.3 Engine bed design and structural strength, lamination, etc Checked: Remarks:
hull must be flat Checked Remarks: 3.1.3 Engine bed design and structural strength, lamination, etc Checked: Remarks:
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strength, lamination, etc Checked: Remarks:
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strength, lamination, etc Checked: Remarks:
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strength, lamination, etc Checked: Remarks:
Remarks:
Todas a la company de la compa
18/74//
1////
Creating holes
3.1.4 Insert properly supported with
front and rear stringers, engine bed attached
Checked:
Remarks:

3.1.5 Clearance to bottom and bed, sufficient Checked: Remarks:	20 mm (3/4")
3.1.6 Fitting and alignment of flexible engine mounts, nominal height Checked: ☐ Remarks:	D6 D4 X
3.1.7 Exhaust hose clamps Checked: Remarks:	
3.1.8 Distance to transom Checked: Remarks:	min 25 mm

3.2 Fuel system

3.2.1 Fuel tank setup, tank location, clamping, connection locations, baffle plates Checked:	
Remarks:	
3.2.2 Proper fuel lines (feed and return), size, fire resistance	
Checked: Copper feed line pipe out dia [mm/in]: Copper return line pipe out dia [mm/in]: Hose inner dia [mm/in]: Remarks:	
3.2.3 Fuel lines, installation, clamping, positioning, suction height Checked:	
Remarks:	
3.2.4 Extra water separator/fuel filters Checked:	
Type: Remarks:	
3.2.5 Required fuel shut off valve Checked:	
Remarks:	
3.2.6 Tank ventilation, min 12 mm (0.5in) installed	
Checked: Remarks:	



3.3 Electrical system

	ematic diagram puired for Certified	Yes No Remarks:	
3.3.2 Voltage		Remarks:	
Checked:			
3.3.3 Battery capac no common g	ity starting groups, roup allowed	Battery types: Lead Acid Battery	AGM
Starboard	Port	Ц	
Checked: Ah: CCA/MCA:	Checked: Ah: CCA/MCA:	(AGM - Absorbed Glass Mat)	
CCA – Cold Cranking A MCA – Marine Cranking	-	Remarks:	
Starboard Cable length batt-engin Cable area [mm²/AWG			
Port Cable length batt-engin Cable area [mm²/AWG			
3.3.4 Battery capac	ity groups, AUX	Battery types: Lead Acid Battery	AGM
Number of groups:			AGIVI
Batteries/group:		(ACM Absorbed Class Mat)	
Charge distributor:		(AGM - Absorbed Glass Mat)	
Group 1	Group 2	Б	
Checked: Ah:	Checked: Ah:	Remarks:	
3.3.5 Charge distrib	outor, separate tery/batteries	Remarks:	
16mm ² red power cable the starter motor discor	e between alternator and nnected at <u>both</u> ends.		
0.75mm² yellow sensor alternator and the start at both ends.			
Checked:			

3.3.6 Heavy loads, connections	Remarks:
Aux 1 Aux 2 Other:	
Bow thruster	
Stern thruster	
Anchor windlass	
3.3.7 IPS power connection	
Checked:	
Remarks:	
3.3.8 Joints readily accessible, harness	Remarks:
routing, clamping, above estimated bilge water level and distance from	
hot areas	
Checked:	
3.3.9 Engine main switch installed	
Checked: On positive (+): On negative (-):	F (4)
Rated Amp: Rated Amp:	
Peak Amp: Peak Amp:	
Remarks:	
3.3.10 Batteries properly secured and	
ventilated	/J// f }
Checked: Remarks:	o 25 mm (1")
Tromano.	
	9 0 -+
	<u> </u>
3.3.11 Alternator sensor cable (yellow), connection point	
Starboard Port	
Checked: ☐ Checked: ☐	
Main switch aux.: Main switch aux.: Main switch aux.:	
Main switch start: Main switch start: Alternator B+: Alternator B+:	
Charge distributor: Charge distributor:	
Remarks:	



3.4 Cooling system

3.4.1 Hot water connections fitted Checked: Yes: No: Remarks:	Mn. 50mm
3.4.2 Extra expansion tank fitted, system volume, height Checked: Yes: No: Remarks:	apgrox.5% MAX apgrox.5% nin apgrox.5%

3.5 Ventilation and sound proofing

3.5 Ventuation and Sound probling	
3.5.1 Total air intake and ventilation area Checked: Intake area [mm²/in²]: Remarks:	
3.5.2 Location of ventilators and air intakes, water ingress prevention Checked:	Remarks:
3.5.3 Electrical suction fan installed (not at air inlet) Checked: Yes: No: Capacity [m³/min cf³/min]: Remarks:	From engine room
3.5.4 Sound proofing Checked: Yes: No: Remarks:	



3.6 EVC, electronic vessel control system

3.6.1 Helm/docking/engine station(s) Checked: Number of standard helms: Number of docking stations: Number of engine stations: Remarks:	
3.6.2 System network requirements Checked: Remarks:	HCU HCU HCU PCU
3.6.3 System configuration, cables, coding, clamping and routing Checked: ☐ Remarks:	Sear/sup panel College Control Instruments Duzzar Sear/sup panel College Coll
3.6.4 Twin engine installation - The display cable is connected to the Y- split marked MULTILINK BREAKOUT (yellow PVC-coating). The sync. cable is connected to the branch marked MULTILINK (yellow marking sleeve). Checked: Remarks:	HCU port MULTILINK HCU starboard Port display Display cable 1.5 m (5 ft) Sync.cable 1 m (3 ft) Display cable 1.5 m (5 ft) Display cable 1.5 m (5 ft)

3.6.5 PCU, HCU and SUS identity corresponds to engine identity (port and stb separate) Checked: Remarks:	
	Constitution of the processing
3.6.6 Location and mounting of PCU/HCU units, dry and accessible, not upside down Checked: Remarks:	
3.6.7 Strain relief on cables for all control units Checked: Remarks:	
3.6.8 Control panel, correctly connected Checked: ☐ Remarks:	Total State of State
3.6.9 Key switch and start stop panel. Relay installed Checked: Number of relays installed: Remarks:	SCH AS STATE OF THE PARTY OF TH
3.6.10 Steering control and connections Checked: Remarks:	Total State of the

3.6.11 Electronic controls, no extensions allowed Checked: Remarks:	THEOTILE CONN X70 Starboard (SEAN X7) Starboar
3.6.12 Instruments, cables, connections Checked: ☐ Remarks:	EVC System Tachometer (EVC ^{EC} -C) Protection plug Multilink/tachometer/ synchronization cable
3.6.13 Connection SUS to PCU and fuel/water level sensor Checked: Remarks:	Water level sender, 2-pole
3.6.14 Fuel level sender installed, calibration(s) done Empty tank calibration (mandatory) Full tank calibration Multi-point calibration Sender type: 3-180 ohm 230-30 ohm Checked:	
3.6.15 GPS installed, NMEA 0183/2000 type signal, configuration Checked: Remarks:	Speedometer Speedometer Speedometer Speedometer MULTILINK MULTILINK MULTILINK MULTILINK MULTILINK MULTILINK MULTILINK MULTILINK MREAKOUT NMEA unit Glaplay GPS Multisensor (transducer)



3.6.16 Autopilot installed Autopilot brand: IMPORTANT! Only the MULTILINK BREAKOUT part of the Y-split cable shall be connected to the EVC-display or the Autopilot- interface. Checked: Remarks:	1. Yargii cole 4. Auto pida 5. Auto pida gareny
3.6.17 Auto configuration completed Checked: ☐ Remarks:	(EVC ^{EC} -C)
3.6.18 Calibration of control Checked: Remarks:	FWD Idle REV Idle Speed REV REV RES Speed REV REV RES Speed REV
3.6.19 IPS drive leg alignment calibration completed Checked: Remarks:	ALIGNMENT TOOL
3.6.20 No external cables connected to the EVC system IMPORTANT! Never cut or modify the Volvo Penta EVC cable harnesses. For extra power supply use the Volvo Penta relay for accessories. Checked: Remarks: 3.6.21 Available options (only EVC ^{EC} -C)	Remarks:
Joystick (calibrated) Trip computer	romano.

3.7 Accessibility for maintenance and repairs

3.7.1 Engine room accessibility Checked: □ Remarks:	Min 180 mm (8°) Min 200 mm (8°)
3.7.2 Oil change and refill Checked: ☐ Remarks:	
3.7.3 Change of oil, fuel, crankcase and air filters Checked: Remarks:	
3.7.4 Check belt tensions and replacement Checked: Remarks:	
3.7.5 Replacement of impeller Checked: Remarks:	
3.7.6 Cleaning of sea water filter Checked: Remarks:	



3.7.7 Fuel system water drainage Checked: ☐ Remarks:	
3.7.8 Electrical components Checked: ☐ Remarks:	
3.7.9 Removal of cylinder head Checked: Remarks:	
3.7.10 Access to IPS unit oil fill, change and filter Checked: Remarks:	
3.7.11 Access to IPS manual steering Checked: Remarks:	

3.7.12 Engine package removal (boat builder must supply instruction if installation is to be certified) Checked: Instruction available: Yes: No: Remarks:	
Time for removal/ refit of engine [h]: Actual: ☐ Estimated: ☐. Flat rate for removal/ refit of engine: D4/D6 IPS 350/400/450/500/600: 5,0 h This is considered normal time.	
3.8 Other accessories and options	
3.8.1 Checked: Remarks:	
3.8.2 Checked:	

Remarks: 3.8.3

Checked: Remarks:

Checked:
Remarks:

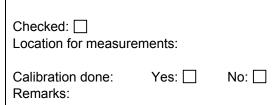
3.9 Installation steps when boat is in water

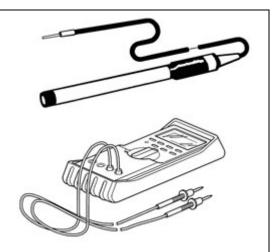
3.9.1 Corrosion measurements

Read "Corrosion Measurement" available at Certified Installation Teamplace for instructions and actions. All measurements can be carried out with a multimeter and a calomel reference electrode (special tools).

A calibration of the reference electrode using a zinc anode is recommended before the measurements are carried out (se "Corrosion Measurements" for procedure information).

The corrosion measurements should be carried out in open water to achieve best results.



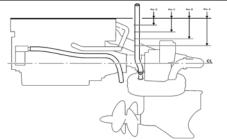


Measurement	Value	Criteria	Met	Action
Potential drive DC Starboard	mV	< -450 mV - seawater < -150 mV - fresh water	Yes 🗌 No 🗌	3
Potential drive DC Port	mV	< -450 mV - seawater < -150 mV - fresh water	Yes 🗌 No 🗌	3
Stray current DC (use multimeter / light bulb)	Ohm	> 5000 Ω	Yes 🗌 No 🗌	5

Checked

Riser fitted Yes: No:

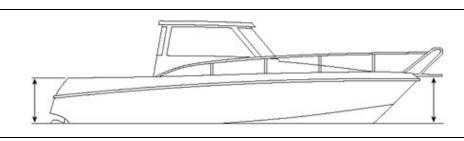
Brand: Remarks:



3.9.3 Measure true waterline as tested (laden), photograph and mark points of reference

Checked:

Remarks:



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3.10 Sea trial (certified installation)

3.10.1 "VP performance report work	Performance report number:
sheet" must be completed if	
installation is to be certified.	

3.11 Sea trial (Quick version, if 3.10.1 is not completed)

3.11.1 Max RPM, speed and displacement Checked: Max RPM: Max RPM: Max speed [knots/mph]: Displacement [kg/lb.]:	Remarks:
3.11.2 Temperature at max RPM at air filter inlet Checked: Temperature [°C/°F]: Ambient [°C/°F]:	Remarks:
3.11.3 Maximum inclination underway (hole speed range) Checked:	Remarks:

3.12 Photos (add below)

